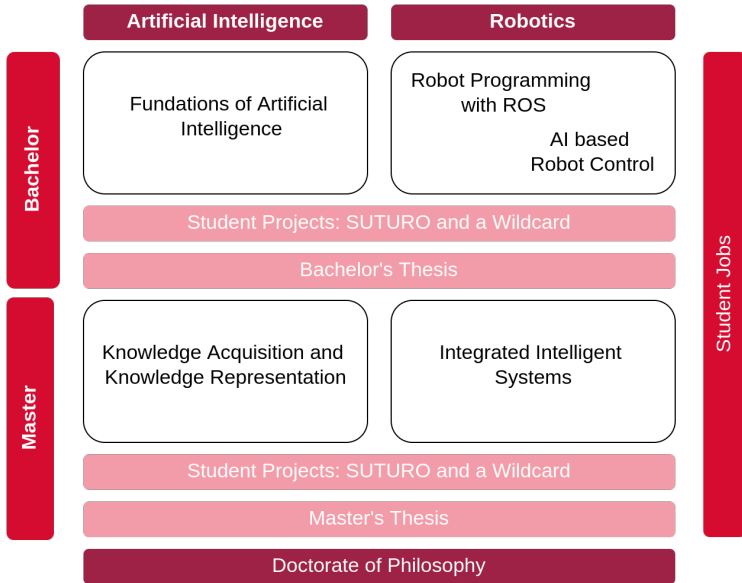


Robot Programming with ROS

1. Introduction, Overview

Arthur Niedźwiecki
19th Oct. 2023





Plan

- 1 Introduction
- 2 Course Overview
- 3 Organizational
- 4 Assignment

General Info

- Lecturers: Arthur, Alina (PhD students at IAI)
- Tutor: Stefan (WiMi at IAI)
- Correspondence: aniedz@cs.uni-bremen.de
- Dates: Thursdays, 14:15 - 15:45, 16:15 - 17:45
- Language: English and German
- Credits: 6 ECTS (4 SWS)
- Course type: practical course
- Course number: 03-IMVP-RPROS (03-BE-710.98b)
- Location: TAB Building, Room 0.30 EG

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Course Goals

Intended Learning Outcomes

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- You can describe how a robot perceives the world.

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- You can describe how a robot perceives the world.
- You understand how an autonomous vacuum cleaner navigates.

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...and get to play with a real little robot!

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<https://www.ros.org/>

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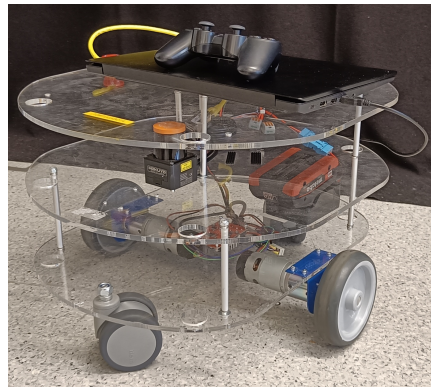
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- *De facto* standard in modern robotics

TortugaBot

- 2 controllable wheels
- 2D laser scanner
- Thinkpad E485 PC with bluetooth
- PlayStation joystick



Rough schedule

Until Christmas 2023: Assignments in simulation

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Jan - Mar 2024: Project in groups

- Controlling TortugaBot
- Heuristic decision-making
- The big day: *competition*

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- Solutions are discussed in the tutorial.

Scheinbedingungen Summary

- Graded homework every week until January, then group project
- Live presentation of the group project, individual grading
- 50 homework + 50 group project = 100 points for final grade
- At least 25 points from the homework to participate in the project
- Final grade: 50 of 100 points - 4.0, 100 of 100 points - 1.0.

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Links

- This lectures website:

<https://ai.uni-bremen.de/teaching/cs-ros-ws23>

- Git reference book:

<https://git-scm.com/docs/gittutorial>

- Assignments repository:

<https://github.com/artnie/rpwr-assignments>

Info summary

Next class:

- Date: 26.10.
- Time: 14:15
- Place: same room (TAB 0.30)

Assignment:

- Due: 25.10, Wednesday, 23:59
- Points: 3 points
- For questions: write me a mail
or ask your colleagues in the StudIP forum

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Assignment goals

Set up your workspace



Set up your Git repository



Get comfortable with Jupyter



Install/Navigate a Linux terminal



Linux

Highly recommended to try Linux!

- Ubuntu 20.04 runs all of the institutes robot software
- ROS is best supported for Ubuntu 20.04
- Natively communicate with the TortugaBot in the project
- You can break everything

Ubuntu 20.04 - your options (Recommended)

Release page:

<https://releases.ubuntu.com/focal/>

- Dual boot to multiple OS (most robust)
Prepare boot stick, choose dual-boot during installation

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<https://www.virtualbox.org/>
- WSL2 - Windows Subsystem for Linux (best for Windows)
Full Ubuntu 20.04 CLI under Windows

[https://ubuntu.com/tutorials/install-ubuntu-on-wsl2-on-windows-10\](https://ubuntu.com/tutorials/install-ubuntu-on-wsl2-on-windows-10)

Robot Operating System (Recommended)

ROS Noetic runs on Ubuntu 20.04

- Installation guide

<https://wiki.ros.org/noetic/Installation/Ubuntu>

- Open access tutorials

<https://wiki.ros.org/ROS/Tutorials>

Assignments Repository

`https://github.com/artnie/rpwr-assignments`

Q & A

Thanks for your attention!